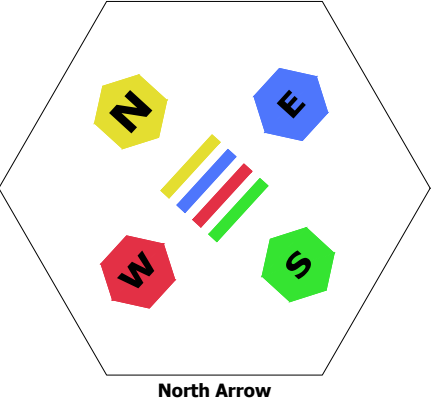




NOTES:

All levels relate to CG (Newlyn) Datum. Established using Network RTK.

LEGEND:

[illegible]

UTILITIES DISCLAIMER:

Layer services include staffed staff and advanced electromagnetic and radar technologies that can detect and identify individuals in the field. The use of these services is subject to the same privacy and information security requirements as other services provided in compliance with 50 USC 12322 Specification. However, the performance of non-real-time survey equipment can be affected by environmental conditions, such as weather, and the accuracy of the detection of all activities on site. Clients should contact regional records and conduct task milestones when necessary.

In most cases, individual services may be distinguished by the degree to which they are represented as a single annotated line, with depths shown for the shallowest utility features. Tracking non-conductive materials, such as underground pipes, is not possible.

Depth readings of underground services/features are generally accurate to $\pm 10\%$ but cannot be guaranteed. Depths typically indicate the top of the service unless otherwise stated, with gravity sensors/brains showing water depths.

Some above-ground features may be obscured at the time of the survey, and GPS operation can be hindered in areas with dense vegetation, debris, or other obstructions.

Dating records provided should be considered indicative only. Datation near located services must be carried out with due diligence (RHS, 1984a).

UTILITY CONFIDENCE LEVELS (From High to Low)

- (A) Horizontal or vertical position detected visually.
 (Outcome: Horizontal (A2096) Vertical (A3096))
- (B3P) Horizontal and vertical position detected by multiple modalities.
 (Outcome: Horizontal (A2096) Vertical (A3096))
 (Estimated Accuracy: ± 3000 cm $\pm 10\%$ of detected range)
- (C2) Horizontal or vertical position detected by multiple modalities.
 (Outcome: Horizontal ± 3000 cm $\pm 10\%$ of detected range)
 (Outcome: Vertical ± 3000 cm $\pm 10\%$ of detected range)
- (D3P) Horizontal or vertical position detected via post-processed GPS.
 (Estimated Accuracy: ± 2000 cm $\pm 10\%$ of detected range)
 (Outcome: Horizontal ± 2000 cm $\pm 10\%$ of detected range)
 (Outcome: Vertical ± 2000 cm $\pm 10\%$ of detected range)
- (E2) Horizontal or vertical position detected by a single modality.
 (Outcome: Horizontal ± 2000 cm $\pm 10\%$ of detected range)
 (Outcome: Vertical ± 2000 cm $\pm 10\%$ of detected range)
- (B3P) Horizontal position detected via post-processed GPS.
 (Estimated Accuracy: ± 3000 cm in the horizontal. Depth is unvaried)
 (Outcome: Horizontal ± 3000 cm $\pm 10\%$ of detected range)
- (D3P) Horizontal position detected by a single modality.
 (Estimated Accuracy: ± 3000 cm in the horizontal. Depth is unvaried)
 (Outcome: Horizontal ± 3000 cm $\pm 10\%$ of detected range)
- (A2) Assumed route. Position not detected.
 (Outcome: Assumed route not detected)
- (C2) Route traced from user input and/or detected and converted to visual indicators and surface features.
 (Outcome: Assumed route not detected)
- (D2) Route traced from user input alone.
- (D2) Route traced from user input alone.

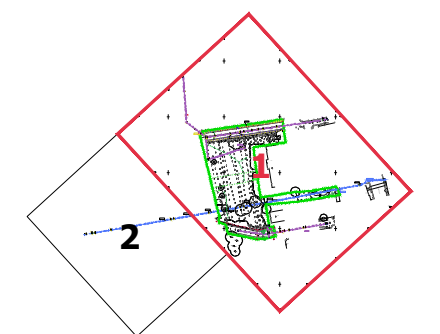
TYPICAL MEASURE DEPTH INDICATIONS		
EXTERNAL MEASURE DEPTH INDICATIONS (mm)	INTERNAL MEASURE DEPTH INDICATIONS	ROUND MEASURE DEPTH INDICATIONS
 MEASURE DEPTH TO CENTER	 MEASURE DEPTH TO RIM	 MEASURE DEPTH

DUCT FOR

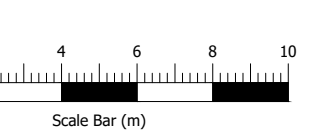
1W:		1 ROW: 1 SINGLE, 0 WIDE, 0 DEEP
2W:		2 ROWS: 1 PLAT
2W:1/2		2 ROWS: 1 WIDE, 2 DEEP
4W:2/2		4 ROWS: 2 WIDE, 2 DEEP
6W:3/2		6 ROWS: 3 WIDE, 2 DEEP
12W:4/3		12 ROWS: 4 WIDE, 3 DEEP

NB: TO BE ADAPTED TO FOR EACH CHAMBER

NOTE: Extents and location of culvert added on 2/2/05/23 to Drawing reference: C5575B-U



SHEET LAYOUT



REV A	DATE 06/25	DESCRIPTION

CLIENT
Onward Homes

**Utility Survey of Land at:
Pennington Street**

Levenshulme Manchester M12 4QJ			
Drawing Ref. L55976			Rev A
Surveyed T.W./S.H	Drawn J.Macgregor	Checked B.Brady	
Scale 1/200	Date Jan 25	Size A0	No. 01

